ON QUASI-ALGEBRAS AND THE WORD PROBLEM

Slaviša B. Prešić

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1. Let Ω be a nonempty set whose membres we shall call operation symbols. We suppose that with each $\omega \in Q$ a non-negative integer $l(\omega)$ (the length of ω) is associated. Let $\Omega(n)$ denote the set of all ω with $l(\omega) = n$. Further, the members of the set

$$V = \{x_1, x_2, \ldots, x_n, \ldots\}$$

are called variables.

Denote by $Term(\Omega, V)$ the set¹⁾ of all terms built up from the operation symbols and the variables.

By an algebraic law we understand any formula of the form

$$(1) t_1 = t_2$$

where t_1 , $t_2 \in Term(\Omega, V)$.

Denote by L a set of certain algebraic laws (of the form (1)).

Further, let Γ be a given set²⁾ and let F be the free Ω -algebra generated by Γ and satisfying the laws L.

Let $Term\ (\Omega,\ \Gamma)$ denote the set³⁾ of all terms built up from Γ and Ω (i.e. without variables).

$$\omega(t_1,\ldots,t_n)\in Term(\Omega,V)$$
.

For the sets Ω , V we suppose that $\Omega \cap V = \emptyset$ and that the symbols), (, , are not members of $\Omega \cup V$.

Elements of $\Gamma \cup \Omega$ (0) are called *constants*.

¹⁾ It is the smallest set which satisfies the following conditions

⁽i) Ω (0) \subset Term (Ω , V), $V \subset$ Term (Ω , V).

⁽ii) If $\omega \in \Omega$ (n) and $t_1, \ldots, t_n \in Term(\Omega, V)$, then

²⁾ We suppose: $\Gamma \cap (\Omega \setminus \Omega(0)) = \emptyset$, $\Gamma \cup \Omega(0) \neq \emptyset$, $= \notin \Gamma$, $\notin \Gamma$, $\notin \Gamma$, $\notin \Gamma$, $\notin \Gamma$.

³⁾ If in the definition of $Term(\Omega, V)$ (see footnote 1) we put Γ instead of V, we obtain the definition of $Term(\Omega, \Gamma)$.

The elements of F are represented by equivalence classes of the following relation \sim of the set $Term(\Omega, \Gamma)$:

(2) $t_1 \sim t_2$ iff: Term t_2 can be obtained from term t_1 by applying the laws t_2 .

This definition is of any practical value only if we have an algorithm, i.e. a rule for deciding in a finite number of steps whether any two terms t_1 , t_2 are equivalent. The problem of finding such an algorithm is called the word problem (for F).

Such an algorithm is decribed in the book P. M. Cohn, Universal Algebra, 1965. on the pages 155, 156.

We sketch it.

Let M be any subset of Term (Ω, Γ) satisfying the following condition:

(3) For every $t \in Term(\Omega, \Gamma)$ there is at least one element $m \in M$ which is equivalent to t.

Further, let σ : Term $(\Omega, \Gamma) \to M$ be a function satisfying the following conditions:

$$1^{\circ} \sigma(w) \sim \omega$$

 2° If $m \in M$, then $\sigma(m) = m$.

By means of M and σ we define an Ω -algebra F' as follows:

- The elements of F' are just the elements of M.
- Let $c \in \Omega(0)$ and $m \sim c$, where $m \in M$. With the symbol c a noughtary operation of M is associated, determined by the chosen element m.
- Let $\omega \in \Omega(n)$, where $n \ge 1$. With the symbol ω the following operation ω_M (of the set M) is associated

$$\omega_M(m_1, \ldots, m_n) = \sigma(\omega(m_1, \ldots, m_n))$$

According to the algorithm (see Theorem 9.1):

(4) If the algebra F' satisfies the laws L then the elements of M are pairwise nonequivalent, i.e.

$$m_1 = m_1 \Leftrightarrow m_1 \sim m_2$$
 (where $m_1, m_2 \in M$)

However, that is not true as the following example shows.

Example 1. Let

$$\Omega = \{*\}, \ l(*) = 2, \ \Gamma = \{a\}, \ L = \{x_1 * x_1 = x_1\}^4$$

For the elements of M we choose:

$$a^2$$
, a^3

where $a^2 \stackrel{\text{def}}{=} a * a$, $a^3 \stackrel{\text{def}}{=} a^2 * a$.

It is obvious that every term $t \in Term(\Omega, \Gamma)$ is equivalent to 3 a^2 or a^3 .

⁴⁾ We have written $x_1 * x_1$ instead of $*(x_1 * x_1)$.

⁵⁾ As a matter of fact every term t is equivalent to the term a.

Further, let o be the following function

$$\sigma = \begin{pmatrix} a^2 & a^3 & a^2 * a^3 & a^3 * a^3 \dots & t \dots \\ a^2 & a^3 & a^2 & a^3 \dots & a^2 \dots \end{pmatrix}$$

(t is any term different from a^2 , a^3 , $a^2 * a^2$, $a^3 * a^3$).

Then the algebra F' is a groupoid defined by the table:

$$\begin{vmatrix} *_{M} \\ a^{2} \end{vmatrix} \begin{vmatrix} a^{2} & a^{3} \\ a^{2} & a^{2} \end{vmatrix}$$
 $\begin{vmatrix} a^{2} & a^{3} \\ a^{2} & a^{3} \end{vmatrix}$

The algebra F' satisfies the law $x_1 * x_1 = x_1$, but on the other hand the terms a^2 , a^3 are equivalent.

One of our purposes is to correct the described algorithm.

2. Let Ω and Γ be given sets. So called *quasi-algebra* is a notion defined by them. The corresponding definition is a bit technically complex, therefore we begin with some examples of quasi-algebras.

Example 2. Let $\Omega = \{*\}$, l(*) = 2, $\Gamma = \{a, b\}$. Let us denote by M the set of the following terms

$$a, b, a*b.$$

Further, let Q be the set of formulas:

(5)
$$a*a=b$$
 $a*b=a$ $a*(a*b)=a*b$ $b*a=a*b$ $b*(a*b)=a$ $(a*b)*a=a$ $(a*b)*b=a*b$ $(a*b)*(a*b)=b$.

Each of these formulas is of the form

$$t_1 * t_2 = t_3$$
 (where $t_1, t_2, t_3 \in M$).

The set Q is an example of a quasi-algebra, i.e. of a quasi-groupoid (of the set $\{a, b, a * b\}$).

More generally, if M is any subset of the set $Term(\Omega, \Gamma)$ containing the elements a and b, then each set M of formulas of the form

$$t_1 * t_2 = t_3$$
 (where $t_1, t_2, t_3 \in M$; t_1, t_2 run over M and for each pair (t_1, t_2) there exists exactly one t_3)

is an example of a quasi-algebra.

In order to work more easily we shall represent the quasi-algebra (5) by the following "table"

Similarly the table

represents a quasi-algebra, with

$$M = \{a, b, (a*a)*b, b*a\}.$$

We now return to the general case in order to define the notion of a quasi-algebra.

Let Ω , Γ be given sets and let M be any subset of $Term(\Omega, \Gamma)$ satisfying the following condition.

(7) If $t \in M$ and if $c \in \Omega(0) \cup \Gamma$ is any subterm of t, then $c \in M$.

Any quasi-algebra Q (related to the ests Ω , Γ , M) is determined with

$$Q = \bigcup_{\omega \in \Omega} Q_{\omega}$$

where Q_{ω} are certain sets of formulas, i.e. equalities.

If $l(\omega) = n \geqslant 1$, then Q_{ω} consists of certain equalities of the form

(9)
$$\omega(t_1,\ldots,t_n)=t \qquad (t_1,\ldots,t_n,\ t\in M)$$

under the condition:

The terms t_1, \ldots, t_n run over M, but two equalities of the form

$$\omega(t_1,\ldots,t_n)=t, \quad \omega(t_1,\ldots,t_n)=t' \qquad (t\neq t')$$

cannot belong to Q_{ω} .

If $l(\omega) = 0$, then Q_{ω} consists of one equality of the form

$$(10) \qquad \qquad \omega = t$$

where $t \in M$.

Example 3. Let $\Omega = \{*, e, f, g\}$, l(*) = 2, l(e) = l(f) = l(g) = 0, $\Gamma = \{a\}$, $M = \{a, e, a * e\}$. The condition (7) is satisfied. Let Q_* be the set of equalities represented by the "table"

Further, let Q_e , Q_f , Q_g be the singletones with the members:

(12)
$$e = e, f = a * e, g = e$$

respectively.

The set $Q_* \cup Q_e \cup Q_f \cup Q_g$ is an example of a quasi-algebra (related to the sets Ω , Γ , M).

3. We are going to study some general properties of quasi-algebras. At first we recall what means that an equality $t_1 = t_2$ is a consequence of given equalities.

Let E be a set of certain equalities containing some constants and operation symbols, but no variables.

We say that a given equality $t_1 = t_2$ is a consequence of E, in symbols $E \vdash t_1 = t_2$, if and only if there is a finite sequence of equalities

(13)
$$u_1 = v_1, \quad u_2 = v_2, \dots, \quad u_n = v_n$$

such that u_n is t_1 , v_n is t_2 and for every $i(1 \le i \le n)$ the equality $u_i = v_i$ satisfies:

 1° $u_i = v_i$ is a member of E; or

2° $u_i = v_i$ is of the form u = u, i.e. u_i and v_i are the same term, or

3° $u_i = v_i$ can be obtained from certain of the equalities $u_1 = v_1$, $u_2 = v_2$, ..., $u_{i-1} = v_{i-1}$ by applying one of the following rules

$$\frac{p=q}{q=p}, \quad \frac{p=q, \ q=r}{p=r}, \quad \frac{p_1=q_1, \ldots, p_k=q_k}{\omega(p_1, \ldots, p_k)=\omega(q_1, \ldots, q_k)}$$

where $l(\omega) = k$, and ω is an operation symbol occurring in some equality of E.

Now let Ω , Γ , L be given. Further, let

(14)
$$L \mid_{Term(\Omega, \Gamma)}$$

be the set of all those equalities which can be obtained from the members of L i.e. from the equalities (1), by all posible replacements of the form

$$x_1 \rightarrow t_1, x_2 \rightarrow t_2, \dots, x_n \rightarrow t_n, \dots$$

where $t_1, t_2, \ldots, t_n, \ldots$ run over the set Term (Ω, Γ) .

Let Q be a quasi-algebra related to the sets Ω , Γ , M. We say that Q satisfies the laws L if and only if each member $t_1 = t_2$ of the set (14) is a consequence of Q.

Example 4. Let $\Omega=\{*\}$, l(*)=2, $\Gamma=\{a\}$, $M=\{a, a*a\}$ and Q a guasi-algebra defined by the table

Let the terms

$$(x_1 * x_2) * x_3, x_1 * (x_2 * x_3)$$

be denoted by $L(x_1, x_2, x_3)$, $R(x_1, x_2, x_3)$ respectively.

From the given quasi-algebra Q it follows the equality

(16)
$$L(a, a, a) = a$$
.

One proof is:

(1')
$$a*a=(a*a)*(a*a)$$
 (This equality is a member of Q)

$$(2') a=a$$

(3')
$$(a*a)*a=((a*a)*(a*a))*a$$
 (From (1'), (2') by the rule

$$\frac{p_1 = q_1, \ p_2 = q_2}{p_1 * p_2 = q_1 * q_2}$$

(4')
$$((a*a)*(a*a))*a=a$$
 (This equality is a member of Q)

(5')
$$(a*a)*a=a$$
 (From (3'), (4') by the rule

$$\frac{p=q, \ q=r}{p=r}$$

i.e.
$$L(a, a, a) = a$$
.

Instead of such a detailed proof we can use the following:

$$L(a, a, a) = (a * a) * a$$
 (Definition)
= $((a * a) * (a * a)) * a$ (For $a * a = a * (a * a)$)

Obviously, this proof corresponds to the usual procedure for finding the value of a given term.

Similarly, for the term a * (a * a), say, we have

$$a * (a * (a * a)) = a * (a * b)$$
 (From (15); b is an abbrevation for $(a * a) * (a * a)$)
$$= a * b$$
 (For $a * b = b$)
$$= b$$
 (For $a * b = b$)

Thus the equality

$$a * (a * (a * a)) = (a * a) * (a * a)$$

follows from the quasi-algebra Q.

Generally, if t(a, *) is any term, then at least one of the equalities

$$t(a, *) = a, t(a, *) = (a * a) * (a * a)$$

follows from Q.

We now return again to the terms $L(x_1, x_2, x_3)$, $R(x_1, x_2, x_3)$.

We claim that the equality

$$L(x_1, x_2, x_3) = R(x_1, x_2, x_3)$$

i.e. the associative law is satisfied in the quasi-algebra Q.

First, let x_1, x_2, x_3 have the values a, a, a respectively. Then we have

$$L(a, a, a) = a$$
 (Equality (16))

$$R(a, a, a) = a * (a * a) = a * b = b$$

i.e.
$$R(a, a, a) = (a * a) * (a * a)$$
.

Does it mean that the quasi-algebra Q does not satisfy the associative law? However, from the quasi-algebra Q we also have the following argument

$$R(a, a, a) = (a * a) * (a * a)$$

$$= b * b$$
(For $a * a = b$, where b is an abbreviation for $(a * a) * (a * a)$)
$$= a$$
(From (15)

Thus, the equality

$$a = b$$
, i.e. $a = (a * a) * (a * a)$

follows from the quasi-algebra Q. From this, we conclude that the set Q is equivalent 0 to the following quasi-algebra Q':

$$\frac{* \mid a}{\mid a \mid} \qquad \Omega = \{*\}, \quad \Gamma = \{a\}, \quad M' = \{a\}.$$

Therefore the quasi-algebra Q obviously satisfies the associative law.

Let us return to the general study.

Let Q be a given quasi-algebra related to the set Ω , Γ , M, where, say

$$M = \{m_i \mid i \in I\}.$$

In general, members of M will be called markers.

Denote by Term(Q) the set of all terms built up from operation symbols of Ω and those members of Γ which occur in some marker.

Suppose that for a term $t \in Term(Q)$ and $m \in M$

$$Q \mid -t = m$$
.

Then we say that m is a marker-value for the term t. Using (7), (9) and (10) it is easy to prove⁷⁾ that

(17) Each term $t \in Term(Q)$ has at least one marker-value.

For some quasi-algebra Q it can happen that

(18) Each term $t \in Term(Q)$ has exactly one marker-value. We say that a quasi-lgebra Q is contractible iff

(19) There are two different⁸⁾ markers m_i , m_j such that $Q \vdash m_i = m_j$. It is easy to see that

 $^{^{6)}}$ We say that two sets E_1 , E_2 of equalities are equivalent iff each member of one of these sets is a consequence of the other set and vice versa.

⁷⁾ By induction on the number of all operation symbols $\omega(l(\omega) \ge 1)$ occurring in the term t, say.

⁸⁾ Different as words, i.e. as terms.

(20) Each term $t \in Term(Q)$ has exactly one marker-value iff the quasi-algebra Q is not contractible.

For instance the quasi-algebra (15) is contractible (because the equality a = (a * a) * (a * a) follows from Q).

Now we give examples of incontractible quasi-algebras.

Example 5. Let $\Omega = \{*, e, f, g\}$, l(*) = 2, l(e) = l(f) = l(g) = 0, $\Gamma = \{a, b\}$, $M = \{a, b, e, f\}$ and Q defined by the table

and the equalities

$$(22) e = e, f = f, g = f.$$

In that case:

- (i) Markers are some constants, i.e. some members of the set Ω (0) $\cup \Gamma$.
- (ii) The equalities of the type (10) have the form $\omega = \omega$ whenever ω is a marker.

Just because of these reasons the equalities $(21)\cup(22)$ represent one part of a definition of an Ω -algebra Q'. Besides these equalities the definition of Q' still contains only the following formulas

(23)
$$a \neq b, a \neq e, a \neq f$$
 $b \neq e, b \neq f$ $e \neq f.$

The Ω -algebra Q', defined by (21), (22), (23), is an Ω -algebra on the set $\{a, b, e, f\}$.

Generally we suppose that

(24) Any Ω -algebra is incontractible

Specially, from this it follows that the algebra Q' is incontractible, whence we conclude that the quasi-algebra Q is incontractible too.

The quasi-algebra Q is an example of so called *letter quasi-algebras*. These quasi-algebras are characterized by the preceding conditions (i), (ii). According to the general suposition (24) we have:

(25) Any latter quasi-algebra Q is incontractible.

We shall now describe a procedure for deciding whether a given quasialgebra is contractible.

First we give an example.

Example 6. Let $\Omega = \{*, e, f\}$, l(*) = 2, l(e) = l(f) = 0, $\Gamma = \{a, b\}$, $M = \{a, b, e, (a*e)*b, (b*e)*(e*e)\}$ and Q represented by (26) and (27), where:

(27) e = e, f = (a * e) * b.

For the m_{ij} it is supposed that they may be any elements of M.

The markers (a*e)*b, (b*e)*(e*e) are called *composite*, because they contain the sign *. Generally, we say that a marker m (of a certain quasi-algebra) is *composite* iff m contains at least one $\omega \in \Omega$, where $l(\omega) \geqslant 1$.

In the first step with each composite marker we associate one new symbol-its new denotation. Let 4, 5, say, be new denotations for the markers

$$(a*e)*b*(b*e)*(e*e)$$

respectively.

According to this we form the following equalities

(28)
$$4 = (a * e) * b, 5 = (b * e) * (e * e).$$

This is the second step of our procedure,

In the *third* step, in the equalities of a given quasi-algebra Q we replace all composite markers by their new denotations. So we obtain the equalities (26'), (27'), where 9 :

(27')
$$e = e, f = 4.$$

Any use of new denotations cannot be creative. From this, investigation whether the given quasi-algebra (25) \cup (27) is conctractible may be replaced by investigation whether the set (26') \cup (27') \cup 28) is contractible (i.e whether from the equalities (26') \cup (27') \cup (28) any of the following equalities

$$a = b$$
, $a = e$, $a = 4$, $a = 5$
 $b = e$, $b = 4$, $b = 5$
 $e = 4$, $e = 5$
 $4 = 5$

follows).

⁹⁾ We suppose that m'_{ii} is obtained from m_{ii} .

The fourth step is investigation of contractibility of the set $(26') \cup (27') \cup (28)$.

Let us denote the set (26') \cup (27') by Q'. This set may be considered as a letter quasi-algebra, with:

$$\Omega = \{*, e, f\}, \quad I(*) = 2, \quad I(e) = I(f) = 0$$

 $\Gamma = \{a, b, 4, 5\}, \quad M = \{a, b, e, 4, 5\}.$

From this and (25) we conclude that Q' is incontractible.

Now we cheek if the equalities (28) follow from O'.

For that purpose from Q' we "calculate" the composite markers (e*e)*b, (b*e)*(e*e). So we have:

$$(a*e)*b=5*b$$
 (For $a*e=5$)
= 4 (For $5*b=4$)
 $(b*e)*(e*e)=a*5$ (For $b*e=a$, $e*e=5$).

The previous calculations constitute the fifth step, which is also the last one,

Thus the equalities (28) follow from Q'.

From this we conclude that the set $(26') \cup (27') \cup (28)$ is equivalent to the set Q', which is incontractible.

Finally, we conclude that the quasi-algebra Q is incontractible.

Note, that the result of investigation essentially depends on the calculations done in the fifth step, Namely:

(29) The quasi-algebra Q is incontractible if and only if the values of composite markers, calculated from the quasi-algebra Q', are equal to their new denotation.

For instance, suppose that we have obtained the equality

$$(a * e) * b = a$$
.

Then from this equality and the equality 4=(a*e)*b it should follow a=4, i.e. the set $(26') \cup (27') \cup (28)$ should be contractible.

In general case we proceede quite similarly as in the given example. The main steps are:

- introduction new denotations for composite terms
- calculation of values of all composite term (related to the new quasi-algebra Q').

In general case we use the equivalence (29), by means of which we finally decide about contractibility of the given quasi-algebra Q.

We have seen that for any letter quasi-algebra Q (with $M = \{m_i | i \in I\}$) there is exactly one Ω -algebra Q' with elements a_i satisfying the equalities defining the quasi-algebra Q. The Ω -algebra Q' is determined by the equalities which define Q plus the inequalities of the following type

$$a_i \neq a_i$$
 (where $i \neq j$).

The similar holds for any incontractible quasi-algebra Q too. Namely if Q is any incontractible quasi-algebra related to the given sets Ω , Γ , $M=m_i$ $i\in I$ defined by the equalities (9) and (10), then there exists exactly one Ω -algebra Q' with elements $m_i\in M$ and satisfying (9) and (10). This algebra Q' is determined by (9), (10) and the inequalities of the following type

$$(30) m_i \neq m_i (\text{where } i \neq j$$

This follows from the fact that the set $(9) \cup (10) \cup (30)$ is consistent (since Q is incontractible). For instance, if Q is the quasi-algebra considered in Example 6, then corresponding Ω -algebra Q' has as elements the terms 10 :

$$a, b, e, (a*e)*b, (b*e)*(e*e)$$

the operation * is defined by (26) and the noughtary operations e, f are defined by (27).

4. Now we return to the word problem posed at the beginning. If the sets Ω (the set of some operation symbols), L (the set of some algebraic laws) and Γ are given then, as we have already seen, the main problem is to describe all members of the corresponding free algebra F. These members are equivalence classes of the relation \sim defined by (2). More precisely this definition reads:

$$(31) t_1 \sim t_2 \quad iff \quad L \mid_{Term(\Omega, \Gamma)} \mid -t_1 = t_2$$

where t_1 , t_2 run over the set Term (Ω, Γ) .

As at the beginning we suppose that there exists a subset M of the set $Term(\Omega, \Gamma)$ satisfying (3).

In addition, for the set M we suppose 11) (7).

Let
$$\omega \in \Omega$$
 (with $l(\omega) = n \geqslant 1$) and $m_1, \ldots, m_n \in H$.

From (3) it follows that the term $\omega(m_1, \ldots, m_n)$ is equivalent to at least one element $m \in M$ i.e. to at least one marker (as before for the elements of M we shall use the name marker). According to this let us form the equality

(32)
$$\omega(m_1,\ldots,m_n)=m$$

where m is a chosen marker equivalent to $\omega(m_1, \ldots, m_n)$. Of course this choice need not be unique.

Further, let $\omega \in \Omega(0)$ and let $m \in M$ be a chosen marker equivalent to ω . Let us form the equality:

$$(33) \qquad \omega = m.$$

¹⁰⁾ As elements we can also use

¹¹⁾ As a matter of fact from (3) it can be easily proved that there exists a new set M_1 satisfying both (3) and (7).

We denote by Q the set of all such formed equalities (32) and (33). The set Q may be considered a quasi-algebra related to the set Ω , Γ , M. For Q we shall also say that it is

a marker quasi-algebra related to Ω , Γ , L.

Our main result is the following theorem.

Theorem. The markers are pairwise nonequivalent if and only if the marker quasi-algebra Q

1° is incontractible, and

2° satisfies the laws L.

Proof. From the definition of Q it follows:

(34)
$$L \mid_{Term(\Omega, \Gamma)} \vdash Q.$$

Using (34) we conclude that the set $L|_{Term(\Omega,\Gamma)}$ is equivalent to the set $L|_{Term(\Omega,\Gamma)} \cup Q$. From this we conclude that the relation defined by (31), can be defined by:

$$(35) m_1 \sim m_2 \quad iff \quad L \mid_{Term(\Omega, \Gamma)} \cup Q \vdash m_1 = m_2.$$

We first suppose that the conditions 1° and 2° hold. As Q satisfies the laws L the set $L|_{Term(\Omega,\Gamma)} \cup Q$ is equivalent to the set Q. From this we conclude that definition (35) may be replaced by:

$$m_1 \sim m_2$$
 iff $Q \vdash m_1 = m_2$.

At last, from the condition 1° it follows:

 $m_1 \sim m_2$ iff m_1 , m_2 are the same term.

Now we suppose that at least one of the conditions 1°, 2° does not hold.

Case: 1° does not hold. Then for some two different markers t_1 , t_2 we have

$$M \vdash t_1 = t_2$$
.

From this and (35) follows that $t_1 \sim t_2$.

Case: 2° does not hold. Then for some different markers m_1 , m_2 we have

$$(36) L \mid_{Term(\Omega,\Gamma)} \cup Q \vdash m_1 = m_2$$

because for at least one law u=v (a member of L) the coresponding marker Q-values 12) of the left and right side will be different, m_1 , m_2 say.

From (35) and (36) it follows that $m_1 \sim m_2$. Thus in both casses 1°, 2° there are two different markers m_1 , m_2 which are equivalent. The proof is completed.

¹²⁾ i.e. related to the marker quasi-algebra Q.

Remark. The condition (3), (5), 1° and 2° are natural because they correspond to the following properties of the free algebra F:

F is an Ω -algebra, generated by $\Omega(0) \cup \Gamma$ and satisfying the laws L.

At the end we give two examples.

Example 7. Let $\Omega = \{*\}$, l(*) = 2, let Γ be any non empty set and let the associative law

$$(37) (x_1 * x_2) * x_3 = x_1 * (x_2 * x_3)$$

be the only member of L. For markers we can take all terms of the form:

$$p_1, p_1 * p_2, (p_1 * p_2) * p_3, \dots$$

i.e. of the form $\prod_{i=1}^{n} p_i$, where $n=1, 2, \ldots$ and $p_i \in \Gamma$.

A coressponding marker quasi-algebra Q can be defined by the equalities of the form

(38)
$$\prod_{i=1}^{n} p_i * \prod_{i=n+1}^{n+m} p_i = \prod_{i=1}^{n+m} p_i.$$

It is easy to see that Q is incontractible and satisfies (37).

For instance, let us compute $(p_1 * p_2) * p_3$ using (38). So we have: value of $(p_1 * p_2) * p_3$

= value of ((value of $p_1 * p_2$) * p_3)

= value of $(A * p_3)$ A is an abbrevation for $p_1 * p_2$

 $= A * p_3$

 $=(p_1*p_2)*p_3.$

Generally, it is true:

value of
$$\prod_{i=1}^{n} p_i$$
, related to Q, equals $\prod_{i=1}^{n} p_i$

i.e. Q is incontractible 13).

Example 8. Let us construct the group G with the presentation

$$G = Gp \{a, b \mid a^2 = b^2 = e, a \cdot b = b \cdot a\}.$$

This problem may be considered as the problem of finding the free algebra F with:

$$\Omega = \{\cdot, e, ^{-1}\}.$$
 $(l(\cdot) = 2, l(e) = 0, l(^{-1}) = 1)$

 $\Gamma = \{a, b\}$, L is the set of the following equalities:

(39)
$$x_1 \cdot (x_2 \cdot x_3) = (x_1 \cdot x_2) \cdot x_3, \quad x_1 \cdot x_1^{-1} = e, \quad x_1 \cdot e = x_1$$

(40)
$$a \cdot a = e, \quad b \cdot b = e, \quad a \cdot b = b \cdot a.$$

It is easy to se that as markers we can use:

$$(41) a, a, b, a \cdot b.$$

¹³⁾ As we can see introduction of new denotations for composite terms is not necessary.

Further, a corresponding quasi-algebra Q is determined by the following equalities

The only composite marker is $a \cdot b$. For it we have

value of $a \cdot b = a \cdot b$ (because in (42) we have the equality $a \cdot b = a \cdot b$).

It can be also proved that (42) satisfies the laws (39) and (40). Thus the terms (41), represent all members of the asked group.